Education & training

Advances in intrauterine technique training

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Background

Virtual reality for practical training has come a long way since the early days of flight simulation during the first part of the last century. It is used in many environments, including spatial awareness, military and surgical training. Three-dimensional physical models (generally plastic) and computer-aided two-dimensional training allow participants to interact visually with objects but usually lack tactile sensation feedback. One improvement is to incorporate haptic technology. By definition, haptics (from the Greek word haptikos, pertaining to the sense of touch and pronounced hap-tiks) is a tactile feedback technology that takes advantage of a user’s sense of touch. Stimulation of the user’s sense of touch is accomplished by applying forces, vibrations, resistances and/or motions back to the user by means of special input/output devices called ‘end effectors’ (jointed mechanical arm pieces), joysticks, data gloves or similar devices. Thus this is the science of applying touch (tactile) sensation and control to interactions within computer applications or graphics. In combination with a visual display, haptic technology can be used as an adjunct to training programmes for skilled tasks requiring hand–eye co-ordination.

Haptic technology

Haptic technology is gaining wider use in several industries, and it has been particularly successful in medicine during the last decade.1 Applications range from training in dental techniques1 and laparoscopic surgery2 to the rehabilitation of patients with cerebral palsy or stroke with functionally impaired upper or lower limbs.1,4 Recently, a group in Illinois, USA reported that they had used haptic technology successfully to assess the variation in surgical proficiency among orthopaedic residency trainees.3 A systematic review of the literature has suggested that simulator training for knee arthroscopy employing haptic technology and computer-generated outcome data enhanced the skills of inexperienced practitioners, and may lead to better surgical performance in the operating theatre.5 Several haptic devices are also being used to good effect in dental training, a field in which more traditional simulation models have not been popular because they lack tactile feedback. The so-called ‘visio-haptic integrated training simulation system’ allows participants to probe and prepare cavities, and uses models of the biomechanical properties of various dental constituents, anatomical structures and dental instruments to provide haptic feedback to the user. It was rated highly by dentists in terms of usability (how useful the system was for improving their hands-on experience), clarity (of haptic feedback from the system), effectiveness (how easily the user could achieve what they wanted to accomplish) and satisfaction (how engaging the system was to use).1

The acquisition of the necessary hands-on skills involving physical interaction with patients (e.g. anatomical manipulation, surgical procedures) by health care professionals (HCPs) is a time-consuming task that has traditionally been based on close supervision by an experienced mentor or trainer, with or without the use of models. Moreover, as the time allotted to training is ever shrinking due to work pressure and restricted funding streams, computer-aided virtual reality medical training offers a promising addition to help HCPs familiarise themselves with the equipment and procedures, and gain confidence in the acquisition of skills in advance of actual patient encounters.

Current training in intrauterine techniques usually involves using a ‘plastic model’, such as a ‘Zoe’. By their nature, these models offer limited potential to recreate the natural anatomical variations that are encountered in real life. The real training experience is gained in the clinical situation, where not only does the trainee...
Connolly and Rybowski have to deal with the procedure itself, but he or she is also affected by the reaction of the patient, who is often anxious and will be aware that the inserter is a trainee. Haptic intrauterine system (IUS) training could be used to reduce the number of times the trainer has to intervene or duplicate procedures (e.g. sounding and device position), which can only improve the experience for the patient.

Mirena® Haptic
Based on this marriage of technologies for the visual and tactile senses, Bayer HealthCare Pharmaceuticals in combination with UK Haptics, Newcastle, UK is developing and designing a Mirena® Haptic model that will allow the user to practise placement of the contraceptive IUS, Mirena. UK Haptics Limited is developing the Haptic program; the software is termed the

Figure 1  The Mirena® Haptic intrauterine system placement simulator. © Bayer HealthCare Pharmaceuticals. Image reproduced with the kind permission of Bayer HealthCare Pharmaceuticals.

Figure 2  Examples of Mirena® Haptic ‘end effectors’. © Bayer HealthCare Pharmaceuticals. Image reproduced with the kind permission of Bayer HealthCare Pharmaceuticals.
‘Clinical Skills Trainer’ or CST. CST provides access to the virtual reality simulator, which will allow users (HCPs) to develop their clinical skills in a virtual environment. The assumption is that users will be gaining Mirena placement confidence and experience.

Mirena Haptic is the first placement simulator and differs from other medical procedure simulators in several ways. The three-dimensional images are of sufficient quality to create a realistic virtual environment. The user views the simulated placement procedure on a three-dimensional screen using three-dimensional glasses (Figure 1), much the same as viewing three-dimensional films in the cinema. The haptic device is fitted with ‘end effectors’ that look and feel like the instruments used for IUS placement (i.e. tenaculum, metal sound, scissors and Mirena inserter) (Figure 2). The simulator reacts in real time to every movement the user makes, and provides feedback during the procedure on the progress made.

There are currently 12 patient scenarios from which the HCP can choose to practise: these include parous and nulliparous women, antverted, retroverted, anteflexed or retroflexed uteri, and women with cervical stenosis requiring dilation. The HCP can view the human anatomy as well as feel it using the end effectors. Each end effector movement provides tactile feedback so all interactions with the anatomy can provide a feeling of resistance similar to the expected sensation in real life. Preparatory steps that would be required in the clinic (e.g. pelvic examination) need to be considered in the correct order, prior to proceeding with insertion. Completion of the insertion procedure tasks is performed in the same way and in the same sequence as it would be during an actual patient encounter. There is also an opportunity to obtain an ultrasound image and check the position of the device after insertion.

Mirena Haptic is designed to be split into component parts so that they fit into small reinforced suitcases, enabling them to be easily transported. It will be available in many countries including the UK, Germany, France, Poland, Australia, Brazil, Canada and the Asia Pacific region. The system is available in English, Spanish, German, French and Portuguese. All models in all languages will have the capability of both hardware and software upgrades.

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References